Electron-Ion Relaxation, Phase Transitions, and Surface Nano-Structuring Produced by Ultrashort Laser Pulses in Metals


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Fundamental physical phenomena in metals irradiated by ultrashort laser pulses with absorbed fluences higher than few tens of mJ/cm² are investigated. For those fluences, laser-produced electron distribution function relaxes to equilibrium Fermi distribution with electron temperature Tₑ within a short time of 10-100 fs. Because the electron subsystem has Tₑ highly exceeding much the ion subsystem temperature Tᵦ, the well-known two-temperature hydrodynamic model (2T-HD) is used to evaluate heat propagation associated with hot conductive electron diffusion and electron-ion energy exchange. The model coefficients of electron heat conductivity κ(ρ,Tₑ,Tᵦ) and electron-ion coupling parameter α(ρ,Tₑ) together with 2T equation of state E(ρ,Tₑ,Tᵦ) and P(ρ,Tₑ,Tᵦ) are calculated.

Modeling with 2T-HD code shows transition of electron heat wave from supersonic to subsonic regime of propagation. At the moment of transition the heat wave emits a compression wave moving into the bulk of metal. Nonlinear evolution of the compression wave after its separation from the subsonic heat wave till spallation of rear-side layer of a film is traced in both 2T-HD modeling and molecular dynamics (MD) simulation.

For fluences above some threshold the nucleation of voids in frontal surface layer is initiated by strong tensile wave following the compression wave. If the absorbed fluence is ~30 % above the ablation threshold than void nucleation develops quickly to heavily foam the molten metal. Long-term evolution of the metal foam including foam breaking and freezing is simulated. It is shown that surface nano-structures observed in experiments are produced by very fast cooling of surface molten layer followed by recrystallization of supercooled liquid in disintegrating foam having complex geometry. Characteristic lengths of such surface nanostructures, including frozen pikes and bubbles, are of the order of thickness of molten layer formed right after laser irradiation.

1 Introduction

Ultrafast energy deposition on a thin surface layer of a metal target irradiated by ultrashort laser pulse [1] leads to formation of pressure wave [2–10] which eventually breaks to a shock wave during its propagation into the bulk of target [11, 12]. Time required for the wave-breaking is shorter if the relative amplitude P/K of compression wave is higher and if the initial compression wave is steeper; here P is a maximum stress in the compression wave profile and K is the bulk modulus of the metal. Pressure P is approximately proportional to absorbed energy Fₑabs, if P is not too high: P < K. At the ablation threshold the pressure in compression wave is ~ (0.1 – 0.2)K. In metals the ablation threshold Fₑabs|abl (for absorbed “abs” fluence) is typically in a range 50 – 200 mJ/cm² [9, 11–13]. As an example, Fₑabs|abl = 65 mJ/cm² has been determined for aluminum in

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works [14, 15], which has been confirmed in the paper [9]. Another research reported gives 30% higher fluence of $F_{abl|sd} = 90$ mJ/cm$^2$ [13]. But for refractory metals e.g., Ta, W the threshold $F_{abl|sd}$ is significantly higher than for aluminum. The new (for two-temperature applications) case of tantalum is considered below.

Due to very high-rate deformation, the material response to loading by a laser-generated ultrashort shock wave may remain elastic even for shock pressures approaching to the ultimate strength of solids [10, 16–26]. The mechanism of laser-induced generation of such shock waves in metals is studied in this work by means of two-temperature hydrodynamics (2T-HD) and molecular dynamics (MD) simulation techniques. 2T-HD method includes an effect of electron pressure on material motion [27], and utilizes a model of solid based on quantum density functional theory. We study a sequence of complex processes leading to generation of shock waves, including 2T electron-ion relaxation, propagation of supersonic electron thermal wave, overheating of the solid and ultrafast homogeneous isochoric melting, and pressure build-up in the heated layer.

It is shown that ultrafast deposition of laser energy $\sim 100$ mJ/cm$^2$ results in formation of a nonequilibrium two-temperature (2T) state lasting several picoseconds. Due to supersonic propagation of heat into the depth of metal the surface layer of $\sim 100$ nm thick is heated, where material gains the internal energy of $\sim 1$ eV/atom and melts quickly. The elastic-plastic transformation and respective structures of elastic-plastic shock waves for different laser intensities are discussed. It is demonstrated that the pressure in an elastic precursor is independent on absorbed energy, but it is coupled with pressure at the melting front.

Expansion of the heated layer leads to strong tensile stress applying to liquid, which triggers nucleation of bubbles followed by foaming of the melt [5, 8, 9, 28–30]. As our simulations indicate, the foam-like material at target surface may expand to a micrometer-sized layer without significant decay of the inter-bubble walls because of the high surface tension of liquid metal. Then the foam begins to collapse, which produces the complex morphology with configurations like bubbles, pikes, mushrooms and other liquid nano-structures. In the meantime the surface temperature drops below the melting point and fast recrystallization initiates freezing of the surface nano-structures. Such nano-structures, including frozen bubbles lying [31–33] beneath the recrystallized metal surface, were found in our experiments and simulations, see discussion below.

## 2 Two-temperature stage

### 2.1 Two-temperature equations

System of two-temperature (2T) hydrodynamics equations is

$$
\frac{\partial x(x^0, t)}{\partial t} = u(x^0, t), \quad \rho(x^0, t) \frac{\partial x(x^0, t)}{\partial x^0} = \rho^0, \quad \rho^0 \frac{\partial u}{\partial t} = -\frac{\partial P(x^0, t)}{\partial x^0},
$$

(1)

$$
\rho^0 \frac{\partial (E_e/\rho)}{\partial t} = -\frac{\partial q}{\partial x^0} - \frac{\rho^0}{\rho} \alpha \cdot (T_e - T_i) + \frac{\rho^0}{\rho} Q - P_e \frac{\partial u}{\partial x^0}, \quad q = -\frac{\rho^0}{\rho} \frac{\partial T_e}{\partial x^0},
$$

(2)

$$
\rho^0 \frac{\partial (E_i/\rho)}{\partial t} = \frac{\rho^0}{\rho} \alpha \cdot (T_e - T_i) - P_i \frac{\partial u}{\partial x^0}, \quad Q = \frac{F_{abs}}{\sqrt{\pi} \tau_L \delta} \exp \left(-\frac{t^2}{\tau_L^2}\right) \exp \left(-\frac{x}{\delta}\right),
$$

(3)

where $x$ is perpendicular to the surface of metal film. $Q$ having dimensionality $W/cm^3$ is a laser energy source term in the electron heat equation (2). Duration of pump laser pulse is $\tau_L$, skin depth is $\delta$, which is a depth of attenuation of incident electromagnetic wave. Time is counted from arrival of the laser pulse maximum to a target surface, while the origin of spatial coordinate $x$ is placed on an initial position of a frontal surface of film.

The unknown functions are: (i) $x(x^0, t)$ giving a lagrangian trajectory of a lagrangian particle in Eq. (1) which was in position $x^0$ prior to laser pulse arrival; (ii) velocity of this particle $u(x^0, t)$; and (iii) the thermodynamic unknowns. In one-temperature (1T) case there are two thermodynamic unknowns, e.g., density $\rho$ and internal energy $E_i$ or density $\rho$ and temperature $T_i$ . All other thermodynamic functions depend on the chosen two functions. In the 2T case there are three thermodynamic variables, e.g., $\rho$ and electron and ion temperatures $T_e$ and $T_i$. There are five equations (1-3) for the five unknowns.
2.2 Two-temperature thermodynamics

Equation of 2T state (Eo2TS) includes the internal energy $E(\rho, T_e, T_i)$ and pressure $P(\rho, T_e, T_i)$, which are functions of both electron temperature $T_e$ and ion temperature $T_i$. The heat conduction coefficient $\kappa(\rho, T_e, T_i)$ and coupling parameter $\alpha(\rho, T_e)$ are also required to solve the system of Eqs. (1-3). Parameter $\alpha(\rho, T_e)$ is practically independent from ion temperature $T_i$ if $T_i$ is higher than Debye temperature $\theta$, which in metals is less or of the order of room temperature. It is shown [27, 34] that this condition is universal for simple (like Al), noble (Au, Cu, Ag, ...), and transition metals (Ni, Fe, Ta, ...).

A new Eo2TS and kinetic coefficients of very refractory metal Tantalum are presented in this work. Functions $E(\rho, T_e, T_i = 0)$ and $P(\rho, T_e, T_i = 0)$ representing Eo2TS are obtained from ab-initio DFT (density functional theory) calculations in the $T_i \rightarrow 0$ limit. In DFT calculation of Ta the BCC crystal structure is fixed and density changes as a result of variation of lattice constant. In this approach ions are fixed in their lattice positions at $T_i = 0$. Uniaxial lattice deformations are not considered. Similar works to find Eo2TS have been done previously for nickel [27] and tungsten [35–37]. Non-isotropic lattice deformations such as, e.g., deformations in directions [100], [110], [111], are not considered. Experimental (expr) equilibrium density and lattice constant at the room temperature are: $\rho_{\text{expr}} = 16.69$ g/cm$^3$ and $a_{\text{expr}} = 0.33058$ nm.

To find Eo2TS, the two-dimensional plane $\rho, T_e$ is covered by discrete mesh $\rho_{i,j}, T_{e,i,j}$ with small enough mesh size of density $\rho_{i+1,j} - \rho_{i,j}$ and electron temperature $T_{e,i+1,j} - T_{e,i,j}$. DFT calculations at the mesh nodes $(\rho_{i,j}, T_{e,i,j})$ give pairs of quantities $E_{i,j}$, and $P_{i,j}$ representing Eo2TS. Figures 1a and 1b show the cold pressure curves of Ta obtained by different methods. DFT calculations using generalized gradient approximation (GGA) and local density approximation (LDA) are presented in Fig. 1a, together with a cold pressure curve used in equation of state developed for this work (the curve with jump) and a cold pressure curve calculated using Johnson’s [38] EAM (embedded atom method) potential (the dashed curve with deep minimum). Johnson’s EAM potential overestimates the ultimate tensile strength of Ta. The cold energy curve $E_{\text{cold}}(\rho)$ of internal energy per unit volume (i.e. internal energy density) is shown in Fig. 2a. It is obtained by integration $\int PdV$ of parabolic approximation of cold pressure curve $P_{\text{cold}}(\rho)$ shown in Figs. 1 and 2a. The result of integration was converted from energy per unit mass to energy per unit volume $(\int PdV)/V$.

![Fig. 1](image1.png)

(a) It is known that DFT simulations (circles, diamonds) determine an equilibrium density $\rho_0|_{\text{DFT}}$ with few percents error; LDA is shown by diamonds, GGA - by circles. But DFT results scaled to the experimental density as $\rho \rightarrow ((\rho_0)_{\text{expr}})/(\rho_0)_{\text{DFT}} \rho$ agree well with EOS (Equation of State) for Ta (the blue curve $P_{\text{EOS}}(\rho)$) and with Johnson’s EAM potential (the red dashed line), as it is demonstrated on the right panel (b). The pressure jump in the function $P_{\text{EOS}}$ at expansion ratio $V/V_0 = 1.17$, where $\rho = 14.23$ g/cc and $P = -21.7$ GPa, approximates nucleation of voids and fracture in stretched material. Tensile stress in the nucleation point is 0.6 fraction of the stress in the spinodal “sp” (see Fig. 2a) minimum $\{\rho_{\text{sp}} = 10.09$ g/cm$^3, P_{\text{sp}} = -36$ GPa$\}$ defined by DFT calculations, expansion ratio the spinodal “sp” to nucleation point is 1.41. (b) The same pressure curves, as in the left panel (a), are plotted up to higher compressions and expansions. They are plotted together with shock Hugoniot [39]. DFT data are scaled to the experimental equilibrium density.

We separate electron contributions, associated with electron excitations, from energy and pressure in cold solid, as it is done in the Mie-Gruneisen approximation of EoS. Energy and pressure of Eo2TS are represented
as sums of cold energy and pressure curves and electron thermal contributions to energy and pressure. The cold curve for energy is shown in Fig. 2a. Electron thermal contributions \( E_e(\rho, T_e) \) and \( P_e(\rho, T_e) \) are shown as arrows in Fig. 2a. The arrows shift the curves \( E \) and \( P \) up from the cold curves, because \( E \) and \( P \) are sums of cold and thermal contributions:

\[
E(\rho, T_e, T_i = 0) = E(\rho, T_e = 0, T_i = 0) + E_e(\rho, T_e),
\]

\[
P(\rho, T_e, T_i = 0) = P(\rho, T_e = 0, T_i = 0) + P_e(\rho, T_e).
\]

Here the electron thermal contributions \( E_e \) and \( P_e \) arise from electron excitations in distinction from the well-known Mie-Grüneisen equation of state where the thermal contributions are from equilibrium single-temperature heating with \( T_e = T_i \).

The shifts \( E_e \) and \( P_e \) in sums (4,5) increase when electron temperature \( T_e \) increases. Corresponding dependencies are shown in Figs. 2b and 3b. DFT calculations with pseudopotential, approximating electrons below the upper two shells \( 5d^3 \) \( 6s^2 \), do not allow to include energy losses due to ionization of f-shell. Therefore the curves 1 and 2 in Fig. 2b diverge. In the temperature range shown in Fig. 2b the number of ionized f-electrons is small in comparison with numbers of d- and s-electrons. Appreciable difference between curves 1 and 2 at small ionization degree results from rather large gap of \( \approx 15 \) eV between f- and conducting bands. Ionization leads to increase of the electron heat capacity \( c_e \), as shown in Fig. 3a. It is interesting that the heat capacity \( c_e \) saturates not at the value \( (3/2)k_B (Z_s + Z_d) \) (total removal of degeneration) but in the intermediate region with the significantly lower value \( \sim (3/2)k_B Z_s \). This is particularly evident for such transition metals as Ni or Pt, where number \( Z_d \) is large. In an ionization region the electron Grüneisen parameter decreases, and the growth rate of electron pressure \( P_e \) with temperature \( T_e \) is significantly lower than the growth rate of internal energy \( E_e \), as it is seen in Fig. 3b. The growth rate of \( P_e(\rho_0, T_e) \) with \( T_e \) decreases since energy added to electron subsystem is mainly consumed for ionization of the f-electrons.
For our applications (ablation including 2T effects) it is necessary to consider finite ion temperatures $T_i$. If $T_i > 0$ then we have
\begin{align}
E(\rho, T_e, T_i) &= E(\rho, T_e = 0, T_i = 0) + E_G(\rho, T_i) + [E_e(\rho, T_e) - E_e(\rho, T_i)], 
\tag{6}
\end{align}
\begin{align}
P(\rho, T_e, T_i) &= P(\rho, T_e = 0, T_i = 0) + P_G(\rho, T_i) + [P_e(\rho, T_e) - P_e(\rho, T_i)] 
\tag{7}
\end{align}
or
\begin{align}
E(\rho, T_e, T_i) &= E(\rho, T_i) + [E_e(\rho, T_e) - E_e(\rho, T_i)], 
\tag{8}
\end{align}
\begin{align}
P(\rho, T_e, T_i) &= P(\rho, T_i) + [P_e(\rho, T_e) - P_e(\rho, T_i)]. 
\tag{9}
\end{align}

In Eqs. (6,7) the functions $E_G(\rho, T_i), P_G(\rho, T_i) = \Gamma E_G(\rho, T_i)$ are Mie-Gruneisen approximations for thermal contributions; $E(\rho, T_e = 0, T_i = 0) = E_{\text{cold}}(\rho), P(\rho, T_e = 0, T_i = 0) = P_{\text{cold}}(\rho)$ are cold curves. The usual Gruneisen parameter is $\Gamma$. In addition to this ”ion” parameter $\Gamma$, a new ”electron” Gruneisen parameter $\Gamma_e$ appears $P_e(\rho, T_e) = \Gamma_e E_e(\rho, T_e)$. DFT calculations show that the electron parameter $\Gamma_e \approx 1.1$ is smaller than the ion parameter $\Gamma \approx 2$. The Fermi free electron model gives $\Gamma_e = 2/3$. The electron contribution is already included into 1T equation of state where $T_e = T_i$. Therefore, we extract quantities $E_e(\rho, T_i), P_e(\rho, T_i)$ in the second terms of equations (6-9). In our applications the ion temperatures are limited to relatively small amplitude much below the Fermi temperature. For such case the functions $E_e(\rho, T_i)$ and $P_e(\rho, T_i)$ are small.

We write $E_G(\rho, T_i), P_G(\rho, T_i)$ in (6,7) and $E(\rho, T_i), P(\rho, T_i)$ in (8,9). In those expressions, taken from one-temperature (1T) case, we change common (in 1T case) for electrons and ions constant $T$ to the ion temperature $T_i$. In condensed phase there are weak dependencies of electron contributions $E_e(\rho, T_e), P_e(\rho, T_e)$ from density $\rho$. This means that those electron contributions weakly influence the elastic constants. Therefore, the replacement $T \to T_i$ done above means we neglect influence of electron temperature $T_e$ on elastic constants in this approximation. Influence of electron temperature $T_e$ onto elastic constants is important in semiconductors and dielectrics where the weakening of stiffness of solids follows from softening of chemical bonds due to excitation of electrons into conduction bands, see, e.g., [40-42]. This is a reason for non-thermal melting in semiconductors and dielectrics.

From the other hand, some materials demonstrate strengthening of elastic constants with increase of $T_e$, see Refs. [35, 40, 43]. Below we will neglect possible hardening of metal at high temperatures $T_e$, which must be relatively small. The replacement $T \to T_i$ allows us to use 1T equation of state to describe ion subsystem. DFT
simulation of energy and pressure for condensed state with excited electron subsystem together with moving ions (MD combined with 2T DFT) is difficult to perform, because it requires a dense 3D mesh in \(\{\rho, T_e, T_i\}\) space.

Analytical approximations of electron contributions (4,5) introduced above and shown in Fig. 2a are

\[
E_e = \left(\frac{\mu}{\mu_0}\right)^{-0.1} \frac{0.09 T_{ekK}^2}{1 + 5 \cdot 10^{-4} T_{ekK}^{-2.7}} (1 + 1.5 \cdot 10^{-5} T_{ekK}^{-2.7}),\quad 10^9 [\text{J/m}^3]
\]

\[
P_e = 1.09 (\rho/\rho_0)^{0.05} [0.09 T_{ekK}^2 (-At + 0.5) + (1.4 T_{ekK}^{1.15} - 11)(At + 0.5)] + 0.58259\ [\text{GPa}],
\]

where \( At = \arctan[(T_{ekK} - 13)/2]/\pi, \) temperature \( T_{ekK} \) is measured in [kK], and the equilibrium density \( \rho_0 = 16.69\ \text{g/cm}^3 \). Functions (10) and (11) approximate results of DFT calculations. They are used in our 2T hydrodynamics (2T-HD) simulations to trace thermal and hydrodynamic evolution of an irradiated Ta target. Influence of density variations near equilibrium \( \rho_0 \) is small for electron temperatures below 5 eV, which is in the range of our interest. But for higher electron temperature, the cohesion effects become weaker than thermal effects when \( T_e \) increases above \( \sim 10\ \text{eV} \). Then, electron energy density \( E_e \) and electron pressure \( P_e \) significantly increase with increase of density at fixed temperatures \( T_e, T_i \).

2.3 Two-temperature electron heat conduction and electron-ion coupling

Electron-ion coupling parameter \( \alpha \) for Ta has been calculated in [34]. The parameter \( \alpha \) defines rate of cooling of electron subsystem as result of energy transfer to ions, see heat balance equations (2) and (3). In case of Ta the coupling parameter

\[
\alpha(\rho, T_e) \approx 1.27 \cdot 10^{17} (\rho/\rho_0) \quad [\text{W/m}^3/\text{K}]
\]

weakly depends on electron temperature. This is consequence of large width of a d-band, spreading significantly above the Fermi energy level \( \mu(T_e = 0) \). In our approximation (12) for Ta, we neglect the \( T_e \)-dependence. For aluminum the situation is similar, see Ref. [34, 44–46].

There are significant \( T_e \)-dependencies in cases of metals with the upper edge \( \varepsilon_2 \) of a d-band of the order of 1 eV or less [34, 44, 47]. The value \( \varepsilon_2 \) is measured from Fermi level \( \mu(T_e = 0) \). It may be above or below this level. Positive values correspond to transition metals (e.g., Ni), while negative - to noble metals (e.g., Au).

Two-temperature electron heat conduction coefficient has been adopted based on assumptions and calculations done in [34]. In 2T-HD code we use the following approximation

\[
f_{\text{lin}} = 0.016 T_{ekK}, \quad f_{\text{sat}} = 0.063, \quad a = (f_{\text{lin}}^{-2.5} + f_{\text{sat}}^{-2.5})^{-0.4}, \quad \kappa_{\text{low}} = T_{ekK}/a, \quad \kappa_{\text{high}} = 520 + 0.12 (T_{ekK} + 7)^2,
\]

\[
\kappa(\rho, T_e, T_i) = (\rho/\rho_0)^3 (\kappa_{\text{low}}^{-1} + \kappa_{\text{high}}^{-1})^{-1} \quad [\text{W/m/K}],
\]

where the electron and ion temperatures \( T_{ekK}, T_{ikK} \) are measured in kK, and \( \rho_0 = 16.654 \ \text{g/cm}^3 \).

3 Experimental setup

Ultrafast imaging interferometry [48] was applied to record expansion dynamics of a sample surface, heated by femtosecond laser pulses, with temporal and spatial resolution. The samples were polycrystalline tantalum films with thickness 0.7-1.4 microns deposited onto glass substrates. The source of femtosecond pulses was a high power Cr:forsterite laser system. This system generates pulses of 80 fs duration at a wavelength of 1240 nm [49]. The laser beam was split into a high-power pump beam and a weaker probe beam. The time interval between the pump and probe pulses was varied by the optical delay line. Probe pulse was a second harmonic with wavelength 620 nm. The p-polarized pump beam at a fundamental wavelength was focused on a surface at an angle of incidence 45 degree in air. Due to oblique illumination, a focal spot at a target surface has elliptic shape with semiaxis ratio which equals to \( r_{0x}/r_{0y} = 1/\sin 45^\circ \). Fluence distribution along a Ta film boundary is \( F(x, y) = F_0 \exp(-x^2/r_{0x}^2 - y^2/r_{0y}^2); \ r_{0y} = 42 \ \text{microns}. \) The diagnostic part of the setup is based on a Michelson interferometer in imaging configuration. Fourier processing of interference patterns ensured the accuracy of surface displacement at \( \pm 1 \ \text{nm} \).

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The ablation threshold measured using well known technique [50] for incident fluence was $F_{\text{inc\,abl}} = 0.31 \, \text{J/cm}^2$. Reflection coefficient of Ta at the ablation threshold and for pump wavelength is $R = 0.38$. The coefficient $R$, important for quantitative comparisons with simulations, was specially measured in our experiments. This gives value $F_{\text{abs\,abl}} = (1 - R) F_{\text{inc\,abl}} = 190 \, \text{mJ/cm}^2$ for absorbed energy at an ablation threshold. In the experiments the displacement histories $h(t)$ of irradiated surface were measured. The surface velocity profiles $u(t)$ were evaluated by differentiating the measured $h(t)$ dependencies, see below.

### 4 Separation of compression wave from a heated layer

#### 4.1 Two-temperature thermal and hydrodynamic phenomena

Description of two-temperature relaxation shown in Fig. 4a follows from solution of 2T-HD equations (1-3). Eq2TS (Equation of 2T State) in forms (10) and (11) together with coupling parameter (12) and heat conduction coefficient (13) are used. In Figs. 4 and 5 the absorbed energy is $F_{\text{abs}} = 200 \, \text{mJ/cm}^2$, duration of Gaussian pulse is $\tau_P = 100 \, \text{fs}$, thickness of skin-layer is $\delta = 15 \, \text{nm}$. 2T relaxation lasts relatively long time, see Fig. 4a. Maximum ion temperature achieved after 2T relaxation is near $\approx 6 \, \text{kK}$. It is achieved in time interval 12-16 ps. After 2T relaxation the 1T regime is established, and the maximum on temperature profile begins to decrease with time as a result of heat conduction to the bulk of target having room temperature.

![Fig. 4](image)

**Fig. 4** 2T relaxation after action of laser pulse; tantalum, $F_{\text{abs}} = 200 \, \text{mJ/cm}^2$, $\tau_P = 100 \, \text{fs}$. (a) Notes near the curves show time instants in ps: $e$ - $T_e$, $i$ - $T_i$. Three empty circles correspond to position and temperature $T_i$ at the melting front at time instants 4, 16, and 30 ps. Temperatures $T_i$ at the first two time instants are higher than the triple point temperature 3290 K of Ta, since at those instants melting process takes place under significant external (external relative to the melting zone where the solid-liquid transition locates) pressure, see text. (b) Transition from electron pressure $P_e$ dominated regime at the beginning of 2T stage to the ion pressure $P_i$ dominated regime at the end of 2T stage; $P_e(x,t = 1 \, \text{ps})/P_i(x,t = 1 \, \text{ps})|_{\text{max}} = 15$. Digits near the curves give time instants, $e$ : $P_e$, total : $P = P_e + P_i$. The chain of small circles show instant positions of a set of Lagrangian particles $x(x^0,t)$ at the $(x,p)$-plane, see Subsection 2.1 for definition of $x(x^0,t)$.

Propagation of melting front from left side to right is marked in Fig. 4a by sequence of three empty circles. We see how the front decelerates by comparing the distances and corresponding time instants between the empty circles. There is a melting zone around the melting front. In this zone solid gradually transfers into liquid through a two-phase solid-liquid phase transition. Pressure at the melting front gradually decreases at acoustic time scale $t_a$. At the instants 4, 16, and 30 ps, corresponding to the sequence of three empty circles in Fig. 4a, the pressures in the melting zone decrease from 43 GPa to 21 GPa, and then to 0.8 GPa. The maximum of pressure $P_{\text{max}}(t)|_{\text{compr}}$ in a compression wave passes melting front at $t \approx 11 \, \text{ps}$; $P_{\text{max}}(t = 11 \, \text{ps})|_{\text{compr}} \approx 27 \, \text{GPa}$. An acoustic wave gradually develops into combination of a positive pressure wave and negative pressure wave [5, 8, 51–55]. Its amplitude for absorbed fluence $F_{\text{abs}} = 200 \, \text{mJ/cm}^2$ is significantly below the bulk modulus of Ta: $K = 200 \, \text{GPa}$. Therefore we speak about a weakly non-linear acoustic wave. The zero pressure value, separating positive and negative parts of an acoustic perturbation, passes through a melting zone at $t \approx 40 \, \text{ps}$. Acoustic time scale is $t_a = d_T/c_s$, where $d_T$ is a thickness of a heated layer, $c_s$ is a speed of sound. Value

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\( t_s \approx 20 \) ps if we take thickness of molten layer \( x_m(t) \) at \( t = 30 \) ps, \( x_m(30) \approx 70 \) nm and speed of sound \( c_s \approx 4 \) km/s.

Expansion of target boundary into vacuum is driven by the total pressure \( P = P_e + P_i \). During the short 2T stage, main driving pressure in this sum is changed from \( P_e \) to \( P_i \), see Fig. 4b. At time instant \( t = 1 \) ps, ratio of electron to ion pressure is 15. The 2T stage is short in the sense that temperature equilibration time \( t_{eq} \) is shorter than acoustic time \( t_s \). System of 2T hydrodynamics equations (1-3) is written in Lagrangian space coordinate \( x^0 \). Increment of mass of column per column cross-section area is \( dm = \rho_0 dx_0 \) g/cm², where \( \rho_0 \) is initial density of homogeneous target prior to pulse action.

Instant positions at \( t = 7 \) ps of Lagrangian particles are shown in Fig. 4b by small circles. The left edge particle is strongly expanded because here pressure drops to vacuum value. Density of Lagrangian particles is too low to follow the evaporation process since physical density contrast between condensed phase and vapor is very high - 3-4 orders of magnitude for the value of absorbed energy corresponding to Figs. 1. We clearly see evaporation in molecular dynamics (MD) simulation described below. Dynamically the evaporation is insignificant in our conditions of very short laser pulse of moderate intensity. Indeed, vapor pressure is many orders of magnitude less than pressures created in condensed matter as result of laser heating. Amount of evaporated mass is very small, thickness of evaporated layer is less than 1 nm [8].

Instant concentration of evaporated atoms decreases from left to right in direction of \( x \)-axis in Fig. 4 due to decrease of ion temperature. There is pure vapor to the left from the boundary of the liquid spallation layer. Above ablation threshold there is a foam region (see next Section). It is located between the liquid spallation layer and the continuous bulk of a target. Concentration of evaporated atoms inside bubbles in foam decreases from left to right - from external to internal bubbles.

Fig. 5 shows how a shift \( h(t) = [x(t) - x(-\infty)] \) of Ta boundary and its velocity \( \dot{h}(t) \) depend on time. Time is reckoned from the maximum of a pump pulse \( Q \) in Eq. (3); trajectory of Ta boundary is \( x(t) \). The Lagrangian particles near the left target edge move to the left side in Fig. 4. For the first time, computed and experimental measurements clearly show existence of an acceleration stage. Previously this stage looks like a jump from zero to maximum velocity. The acceleration stage covers time interval from the arrival of pump and up to the maximum of velocity \( \dot{h}(t) \). We connect this rather slow acceleration with large density of Ta and rather long 2T stage during which the transition from \( P_e \) to \( P_i \) drive takes place.

\[ h, \text{ nm} \]

\[ u, \text{ km/s} \]

\[ t, \text{ ps} \]

**Fig. 5** a) Time-dependent displacement \( h(t) \) of Ta boundary into the vacuum side after laser irradiation. 2T-HD simulation shown by solid line, while pump-probe experimental measurements by circles and squares: \( F_{\text{abs}} = 200 \) mJ/cm² for 2T-HD (for 2T-HD spatial profiles are shown in Fig. 4), and \( F_{\text{abs}} = 220 \) mJ/cm² - circles, \( F_{\text{abs}} = 180 \) mJ/cm² - squares. Experimentally measured ablation threshold is \( F_{\text{abs|abl|}} \approx 200 \) mJ/cm². b) Expansion velocities \( u(t) = \frac{dh(t)}{dt} \) obtained in 2T-HD (thick blue curve) and from pump-probe measurements: \( F_{\text{abs}} = 220 \) mJ/cm² - red curve, \( F_{\text{abs}} = 180 \) mJ/cm² - black curve.
4.2 Emission of compression wave during deceleration of supersonic heat wave

Let us consider formation of shock as result of ultrashort laser pulse action. There are absorption of pump pulse, 2T-stage, and acoustic stage. The compression wave is formed during transition from 2T-stage to acoustic stage. 2T-stage is rather long in time, see delay between the times of pump arrival and the velocity maximum in Fig. 5b. There are heat conduction and expansion of a heated layer into bulk of metal, electron heating of ions, and formation of pressurized layer with pressure distribution \( P(x; t_{eq}) \). It is important that duration of 2T-stage \( t_{eq} \) is shorter than acoustic time scale \( t_a = d_T/c_s \). There is acoustic decay of pressure distribution \( P(x, t_{eq}) \) into two \( P_- + P_+ \) running waves. In linear approximation we have \( P_- = (1/2)P(x + c_s t; t_{eq}) \), \( P_+ = (1/2)P(x - c_s t; t_{eq}) \). The left (see definition of left-right directions in Fig. 4) wave \( P_- \) is reflected from vacuum boundary \( P_-(-x) \rightarrow -P_-(-x) \), changes sign of pressure amplitude \( -P_-(-x) \), and begins move to right \( P_{refl} = -(1/2)P(-x + c_s t; t_{eq}) \) in the wake of compression wave \( P_+ \). There is approximately double decrease in amplitude of positive pressure during transition from 2T-stage to acoustic stage, see Fig. 6a. After that the maximum pressure \( P_{max}(t) \) in a compression wave stays constant in time up to the moment \( t_2 \) when the spatial position \( x_{max}(t) \) of the maximum \( P_{max}(t) \) begins to coincide with position \( x_{sw}(t) \) of a shock. Shocks appears at the instant \( t_{focus} \) due to non-linear focusing of characteristics. Breaking of Riemann wave takes place before the instant \( t_2 \). After the instant \( t_2 \) the maximum pressure \( P_{max}(t) \) (shock amplitude after \( t_2 \)) slowly decreases with time since the flow behind a shock is subsonic and rarefaction wave attenuates the shock.

![Fig. 6](image-url) (a) Formation and acoustic decay of pressure wave in Nickel which absorbs 0.6 J/cm² energy. Molecular dynamics simulation; pulse duration is 100 fs. The digits near curves give time instants in ps. Those crosses show positions of melting front \( x_{mel}(t) \). (b) Decrease of “differential” Gruneisen parameter \( dp/dE|_\nu \) during melting. Here a value \( dp/dE|_\nu \) is plotted as a function of temperature \( T \) or pressure \( P \) along isochoric line \( \rho = \rho_0 \). Rigidity of matter drops down in two-phase crystal-liquid zone. This zone is separated from solid by solidus and from liquid by liquidus. The solidus and liquidus are selected by notes “sol” and “liq”.

The pressure profiles in Fig. 6a shifts to the right side with velocity \( \approx 7.1 \) km/s. This propagation velocity is significantly above elastic speed of sound \( c_{elast} \approx 6 \) km/s in Ni. In usual conditions the speed of propagation of elastic compression wave deviates from speed \( c_{elast} \) slightly, not more than 50-100 m/s. Above this limit, the elastic wave in usual conditions is accompanied by plastic shock. In our molecular dynamics simulation, the solid Ni locates at the right side relative to melting front \( x_{mel}(t) \) shown by the crosses in Fig. 6a. This remains in elastic uniaxial compression state. No plastic transformations take place in spite of huge values of shear stresses.

In Fig. 6b dependencies along the particular isochoric line \( \rho = \rho_0 \) are shown. Density for this isochoric line corresponds to equilibrium density \( \rho_0 \) of Ni. Rigidity of Ni decreases when the isochoric line intersects a melting curve. Figuratively speaking, two continuous parts and one steep part of dependencies shown in Fig. 6b resemble a binodal curve at the \( \rho, T \) phase plane. The steep part corresponds to the interval of the triple point. The steep decrease of rigidity of matter leaves a trace in profiles of propagating compression wave shown in Fig.
6a. We see that a pressure profile is steeper below the point marked by the horizontal straight line in Fig. 6a. This straight line corresponds to pressure in the intersection point of the curve of liquidus and the isochoric curve at the \( \rho, T \) or \( \rho, P \) planes of thermodynamic phase space, see also Fig. 6b. The steeping of the pressure profile appears at the supersonic melting stage. After transonic deceleration of heat wave, the steepening is carried along the characteristics lines together with the value of pressure in the intersection point.

Significant rise in the steeping is the reason of formation of elastic shock with pressure amplitude which equals to the value of pressure in the liquidus/isochoric intersection point. This interesting feature has been marked in our previous papers [56, 57]. Results in those papers have been based on 2T-HD simulations. Here we found an initial amplitude of elastic shock from MD simulations, see also [12]. Let us emphasize that in the 2T-HD simulations both kinks, corresponding to solidus and liquidus, are seen. In molecular dynamics only the upper kink is seen. As was said above, it refers to the liquidus.

![Fig. 7 Distribution of matter involved in flow after action of ultrashort laser pulse. Parameter of pulse are \( F_{\text{abs}} = 270 \text{ mJ/cm}^2, \tau_L = 100 \text{ fs} \). This is MD simulation of freestanding tantalum film. EAM Johnson potential has been used to describe atom-atom interactions. Initial data are taken in accordance with 2T-HD results for this particular laser pulse. We define the bottom as the plane \( x = x_{\text{nucl}}(t) \) at the right side where the largest bubbles end. The \( x \)-axis is directed from left to right as in Figs. 4. Ratio of vertical and horizontal scales is 1:1. Vertical \( (y, z)\)-direction height is 24 nm. Cross section \( y \times z \) of box is \( 24 \times 12 \) in nanometers. We see interesting phenomenon of secondary nucleation exactly near the melting-recrystallization front. Crystal is at the right side from this front. Molten tantalum is at the left side from the front. Instant 188 ps after arrival of pump pulse is shown. Secondary nucleation takes place as result of action of tensile stress wave. This wave appears after reflection of compression wave from the rear-side boundary of a film. Thickness of film is 400 nm. The rear-side boundary is the right side end of the film. It is located more to the right than the shown frame.](image-url)

5 Foaming and freezing

Quickness and smallness (very small depth is heated) of femtosecond pulse is a reason of interesting physical phenomena: super-elasticity of solids, approaching ultimate strength against elastic-plastic transformation [16–24], and nanospallation of liquid layer, where surface tension of bubble foam becomes dynamically significant [8, 29, 31–33]. Spallation of liquid nanolayer with thickness comparable to skin depth \( \delta \) (Subsection 2.1) is a reason for appearance of interference Newton rings [28–30, 58, 59] since so thin layer of molten metal or semiconductor is transparent for probe laser light. Never before spallation layer was so thin to be transparent.

Another unusual physical situation is described in this Section. As a rule, hydrodynamics and solidification are separated due to quickness of hydrodynamics and slowness of solidification. It is difficult to imagine a fountain water jet crystallized in its fly. Formation of icicles is mainly thermal process, if we think about fountain hydrodynamics. Of course, gravity drain of water is significant ingredient of icicles growth. Below we describe nanojets solidified in their flight.

Let’s consider this phenomena. Absorbed fluence \( F_{\text{abs}} \) is the main parameter controlling results of femtosecond action. Below a melting threshold \( F_{\text{abs}|\text{melt}} \) irradiated target remain solid. Between thresholds \( F_{\text{abs}|\text{melt}} \) and \( F_{\text{abs}|\text{nucl}} \) a layer of molten metal keeps its continuity (no nucleation). At a nucleation threshold \( F_{\text{abs}|\text{nucl}} \) first viable nuclei appears. It is important that nucleation takes place appreciably below ablation: \( F_{\text{abs}|\text{abl}} - F_{\text{abs}|\text{nucl}} \sim 0.1 F_{\text{abs}|\text{abl}} \) [31–33]. This is also the consequence of quickness and smallness; in the less quick process the relative gap \( (F_{\text{abs}|\text{abl}} - F_{\text{abs}|\text{nucl}})/F_{\text{abs}|\text{abl}} \) between nucleation and ablation thresholds is smaller. There is no separation of matter in the form of spallation layer in the interval \( F_{\text{abs}|\text{nucl}} < F_{\text{abs}} < F_{\text{abs}|\text{abl}} \). After femtosecond action a metal surface moves into vacuum side and undersurface bubbles grow, but in this interval of values \( F_{\text{abs}} \), a surface tension stops spallation layer in its motion away. After this stop the velocity of boundary changes sign as result of reduction of undersurface bubbles in size. There is a competition between processes of the bubble collapse from one hand and solidification of liquid around a bubble from another hand. Often the solidification wins this competition. In this case bubbles remain under surface in solid matrix around [31–33].
There is an evaporation threshold \( F_{\text{abs, ev}} \approx 1.4 F_{\text{abs, abl}} \) for Ta. There is a liquid spallation layer in the interval \( F_{\text{abl}} < F < F_{\text{ev}} \) between those two thresholds \([8, 53]\). From left to right along \( x \)-axis (see Figs. 4 for definition of direction), in this interval, the ejecta in a plume has following structure: (i) vapor, (ii) spallation layer, (iii) vapor-liquid mixture, (iv) crater bottom, and (v) the rest of a target. Above threshold \( F_{\text{abs, ev}} \) the second link in this chain disappears. At even higher fluences \( F_{\text{abs, ev}} \) vapor becomes hotter and expands faster. This increases a difference between hot vapor in the head of plume and two-phase mixture near the crater bottom, since parameters of two-phase mixture near the bottom do not depend significantly on absorbed fluence. At the instant picture of a developed plume, the bottom bubbles are larger in their sizes than bubbles in the mixture more far from the bottom, see Fig. 7. Hot vapor and hot vapor-droplet mixture move fast, while velocities of liquid films in the bottom part of a plume are low \( \sim 10 – 100 \) m/s. Liquid films form approximately flat segments separating neighbor bubbles in a foam.

The left, middle and the bottom parts of a tantalum plume are presented in Fig. 7. Laser pump pulse comes from the left side. Instant density map is shown in Fig. 7. Fast hot pure vapor moves first. The more to the left, the hotter vapor is. The smallest dots in Fig. 7 correspond to evaporated atoms. Evaporated atoms are presented in vapor, in foam, and inside bubbles. Temperature and atomic concentration of vapor drop down from left to right. Gradually from left to right the pure vapor transfers to the vapor-droplet mixture. Sizes of droplets increase to the right. First, small clusters of atoms appear in vapor environment. At our time scale the droplets appear as result of expansion and disintegration of foam type vapor-liquid mixture, while the smallest clusters may be result of evaporation. Expansion of mixture and inflation of particular bubble are connected with \( x \)-velocity gradient. Much later in time droplets begin to evaporate, while vapor slowly condenses into small droplets \([6, 60, 61]\).

Evolution of small size bubble ensemble near the melting-recrystallization front is shown in Figs. 8. Let us discuss why a cavitation rather late in time (much later than acoustic time scale \( t_s = d_T/c_s \approx 20 \) ps) and exactly at liquid-solid phase boundary appears. Formation of compression wave in 2T-HD and in MD simulations is shown in Figs. 4b and 6a. The wave propagates to the right. In case of film the wave achieves a rear-side of a film. Compression wave reflects as a tensile wave from the rear-side vacuum boundary. This tensile wave propagates back from the right side to the left side. Amplitude of the tensile wave, when it arrives to the phase separation front, depends on absorbed fluence \( F_{\text{abs}} \) (larger \( F \) - then larger amplitude) and thickness of a film \( d \) (larger \( d \) - smaller amplitude). In our case \( (F_{\text{abs}} = 270 \) mJ/cm\(^2\), \( d = 400 \) nm) this amplitude is not enough to cause spallation in solid tantalum. But it is enough to cause cavitation in liquid, since strength of liquid is significantly smaller than strength of solid see Fig. 8 in \([16]\) and \([62]\). The tensile wave comes from the solid side. Therefore it nucleates liquid near the melting-recrystallization front if its amplitude hits into the gap between the maximum liquid strength and solid strength.

![Fig. 8](image_url) Appearance and decay of cavitation near the liquid-solid phase boundary. During decay sizes and number of bubbles decrease. Let us attract reader attention to the unusual shapes of bubbles. Some of them are “sitting” at the phase boundary. In this case part of their surrounding surface is liquid and part is solid. The solid part is approximately flat. Therefore bubbles take beautiful hemispherical (snap) shape. (a) \( t = 188 \) ps. (b) \( t = 199 \) ps. The upper bubble has shape of a hemisphere.

There are primary and secondary cavitations. Primary liquid nucleates at acoustic time scale \( t_s = d_T/c_s \approx 10 – 20 \) ps, where \( d_T \) is thickness of heated layer. Secondary nucleation appears much later. Indeed, pressure wave has to pass twice thickness of a film \( \sim 2 (d - d_T)/c_s \). This situation is similar to the situation discussed in paper \([16]\), where aluminum film was deposited onto glass plate surface. Pump irradiates glass-aluminum surface through glass. Irradiation, firstly, forms molten layer near glass-aluminum boundary and, secondly, it produces compression wave which returns back to the molten layer after reflection from the rear-side. This reflected tensile
wave does not spalled solid, but it causes cavitation when it arrives into liquid. The difference with considered in Figs. 7 and 8 case is that here [16] we don’t have a glass supporting metal against primary cavitation.

Let us pay attention also to the hemispherical bubbles dissected by solid-liquid interface, see Fig. 8b. Deformation of bubbles during their freezing has been described in [33]. But in this work the recrystallization front comes from one side of the bubbles and begins to freeze them. While here (Figs. 7 and 8) the bubbles from their beginning appear at the solid-liquid interface. Another point concerns interesting observations. The secondary cavitation may give explanation to the mysterious phenomenon observed in our recent experiments (unpublished). In experiments with tantalum films, above certain threshold $F_{abs}|_{abl} = 2.5 F_{abs}|_{abl}$ higher than the ablation threshold $F_{abs}|_{abl}$ two craters pattern has been found (one crater is inside another one). First crater appears at the ablation threshold and has depth $h_1 \approx 20 - 30$ nm. At the rather sharp threshold $F_2$ the second crater is formed inside the first one. Its depth at the threshold $F_2$ is $h_2 \approx 70 - 80$ nm. The depths $h_1$ and $h_2$ are close to the depths of primary and secondary cavitations shown in Figs. 7 and 8. Unfortunately, the secondary solid-liquid cavitation in our series of simulations finishes with collapse of secondary bubbles. Also for simulation shown in Figs. 7 and 8 the ratio of thresholds $F_2/F_{abl}$ is smaller than 2.5. But thickness of film 0.4 micron in Figs. 7, 8 is smaller than thickness in experiment 1.4 micron. This fact decreases the ratio $F_2/F_{abl}$.

Above processes of nucleation, expansion of vapor-liquid mixture, formation of foam, and expansion of foam have been studied. We see that the bottom part of a foam expands slowly, velocities here are low $\sim 10$ m/s. The bottom part of foam locates near the bottom of the future crater. At so small velocities, long times (hundreds and thousands picoseconds) are necessary to mechanically disintegrate liquid walls forming foam. During disintegration there is a transit from integrated foam to vapor-droplet mixture. At such long times cooling by electron heat conduction becomes important. Conduction loses into bulk lead to cooling and solidification of molten metal.

The competition between dynamical breaking of internal ties of foam (from one side) and freezing of foam (from the other side) defines late time evolution in the bottom part of a foam. Internal ties form dynamically integrated interconnected structure. Namely this structure resists to stretching of foam. Foam is poor heat conductor. Therefore spallation plate fly away in state of hot molten metal. But the bottom part of a foam loses heat as result of cooling into bulk. Gradually liquid walls forming foam begin solidify. The process of crystallization of liquid walls in motion is shown in Fig. 9.

An aluminum film shown in Fig. 9 has initial spatial dimensions $500 \times 240 \times 24$ nm$^3$; 172 million atoms. Absorbed fluence $F_{abs} = 120$ mJ/cm$^2$ is above ablation threshold by 45%. Strong foaming takes place at this fluence enlarged in comparison with ablation threshold, see Fig. 9a. Stretching of liquid walls separating foam cells leads to decrease of thickness of wall and to decrease of mass per unit of wall surface. Particular wall breaks when its thickness drops down to few interatomic distances. Walls are stretched and therefore they exist in stressed state. Breaking a small hole through the particular wall segment leads to fast expansion of hole. As result this segment disappears and two neighbor cells unify. Neighboring walls dynamically compete with each order. Thinner walls expand faster and disappear.

Very important feature used in MD code is that it includes Monte-Carlo model of electron heat conduction. Electron heat conductivity of metals is much larger than ion heat conductivity, therefore pure MD simulation underestimates substantially the heat propagation in metals at nanoscales, where large temperature gradients are generated by femtosecond laser irradiation. MD combined with Monte-Carlo approach for electron thermal transport has significant advantage over common MD coupled with 1D continuous heat equation - it allows to determine accurately the heat flux through such topologically complicated region as a foam, where heat is transported along branching walls. Green and red colors in Figs. 9b-e separates crystalline metal and melt. Simulations show that at late stages liquid is overcooled, since solidification velocity is limited by which is a few times below velocity $v_{recryst} = \Delta q/\rho \lambda$ in Stefan problem. Here $\Delta q$ is a heat flux jump at a front, $\lambda$ is heat of fusion per unit mass. In those overcooled conditions the nuclei of new crystalline phase appears outside of the crystallization front - at free surface of bubbles and even inside bulk melt, see Fig. 9c. Those nuclei are clearly seen as green spots inside red molten aluminum. Stage of growth of such nuclei inside liquid finishes with formation of polycrystalline solid with nanoscale crystalites. They form a crust between bottom of a foam and bulk metal, see Figs. 9d,e. Evolution of mobile dislocations in thermally stressed solid near recrystallization front is also interesting. Dislocations define motions of spots with tints of green color in crystal under solidification front in Figs. 9b-e.
6 Conclusion

The reasons for formation of complex nanostructures on irradiated metal surface were revealed in this paper for the first time. The main reason is found to be decay of a metal foam resulting in formation of liquid structures like threads/pikes, followed by freezing of those structures. It gives us insight into the physical mechanism leading to a characteristic scale of frozen surface structures, which is of the order of heated depth $d_T \sim 100 \text{ nm}$ produced by heat propagation during electron-ion thermalization stage. The mechanism of nano-structuring is composed of sequence of processes starting from void nucleation in a stretched melt, which is followed by rapid cavitation and expansion of foam-like melt, breaking of foam, and subsequent recrystallization of surface and freezing of foam remnants.

By contrast with theories of interference between incident wave and surface plasmons used to explain appearance of LIPSS (laser induced periodic surface structures), which predict the surface structure scale of the order of wavelength $\sim 1 \text{ micron}$ typical for electromagnetic waves in optical range, our results give much smaller structure scale of the order of heated depth $100 \text{ nm}$. We think that a future complete theory of surface nanostructuring should include both thermomechanical processes and surface interference as well as interplay between them.

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